

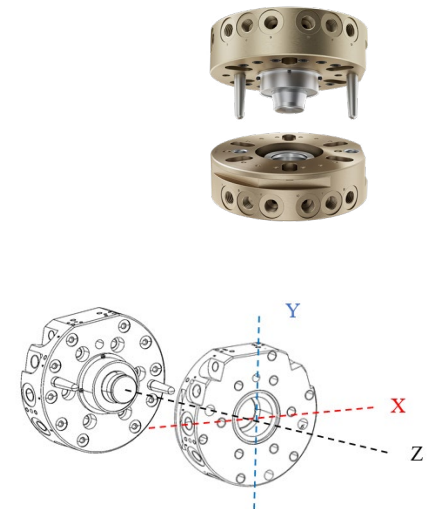


SELECTION GUIDE TOOL CHANGER

Company Address	Contact person Department Phone E-Mail	Date
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Application

1. Gripper and workpiece weight (kg)
2. Robot model (mind the load capacity diagram)
3. Distance to center of gravity (mm)
4. Max. acceleration (m/s^2): in X in Y in Z
5. Max. forces (N): in X in Y in Z
6. Max. moments (Nm): in X in Y in Z
7. Pneumatic pressure applied to tool changer (bar)
8. Number of pneumatic air ports
9. Vakuum transmission: yes no
10. Sensors: piston stroke tool side presence
11. Ambient conditions Temperature
12. Number of robot (R) and tool sides (T): R T
13. Product preselection



Accessories (optional)

Transmission of electrical signals, data and power

14. Protocol
15. Number of electrical contacts/pins
16. Max. voltage (V) Max. current (A)
17. Electrical interface
 - 17.1 Other

Transmission of pneumatics and fluids

18. Medium to be transmitted
19. Number of transmission ports
20. Max. operating pressure (bar)
21. Mechanical interface
 - 21.1 Other



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Tool Rack

22. Tool rack for tool side, if required: tool rack plate tool rack with pillars

23. Description of the application and use case with sketch (show interference contour):

